



LADBROKES Q STRAIGHT, QLD
 Race 1 - ROSEWOOD VETERINARY SERVICE Maiden H - 300M
 15/06/2026 - 18:20:46 PM

RUG	NAME	BOX	TOP SPEED	50M	100M	150M	200M	250M	300M	200M HOME	FINISH TIME
4	Cool Gent	4	72.8KM/H	4.02 [4] 45.0KM/H (7.8M)	6.56 [1] 70.9KM/H (7.4M)	9.03 [1] 72.7KM/H (7.4M)	11.53 [1] 72.1KM/H (6.9M)	14.10 [1] 70.2KM/H (5.6M)	16.73 [1] 67.4KM/H (4.3M)	10.17 70.5KM/H (6.1M)	16.73 [1]
2	All On Black	2	73.3KM/H	4.13 [7] 43.9KM/H (6.7M)	6.71 [6] 69.7KM/H (5.3M)	9.17 [5] 73.2KM/H (4.7M)	11.64 [3] 72.8KM/H (4.1M)	14.17 [2] 71.2KM/H (3.8M)	16.74 [2] 68.3KM/H (3.3M)	10.03 71.3KM/H (4.0M)	16.74 [2]
8	Atomic Beau	8	71.8KM/H	3.98 [2] 45.5KM/H (10.2M)	6.60 [3] 68.6KM/H (9.7M)	9.11 [2] 71.8KM/H (9.1M)	11.64 [2] 71.2KM/H (8.0M)	14.23 [3] 69.5KM/H (6.9M)	16.85 [3] 67.2KM/H (5.4M)	10.25 69.9KM/H (7.4M)	16.85 [3]
1	Aston Hero	1	72.0KM/H	4.05 [5] 44.7KM/H (4.6M)	6.65 [5] 69.2KM/H (1.6M)	9.16 [4] 71.7KM/H (1.6M)	11.71 [5] 70.8KM/H (2.8M)	14.28 [4] 70.0KM/H (3.8M)	16.89 [4] 68.4KM/H (4.4M)	10.24 70.2KM/H (3.1M)	16.89 [4]
5	Aces Smith	5	71.0KM/H	3.94 [1] 45.9KM/H (9.3M)	6.58 [2] 68.2KM/H (9.1M)	9.12 [3] 70.9KM/H (8.5M)	11.69 [4] 70.1KM/H (7.6M)	14.33 [5] 68.2KM/H (7.0M)	17.02 [5] 66.9KM/H (6.4M)	10.44 69.0KM/H (7.4M)	17.02 [5]
3	Loving Jess	3	71.2KM/H	4.00 [3] 45.2KM/H (4.9M)	6.64 [4] 68.2KM/H (1.9M)	9.18 [6] 71.0KM/H (2.0M)	11.78 [6] 69.1KM/H (3.0M)	14.40 [6] 68.8KM/H (2.1M)	17.03 [6] 66.2KM/H (1.8M)	10.39 68.7KM/H (2.2M)	17.03 [6]
6	Littler	6	70.8KM/H	4.09 [6] 44.3KM/H (9.4M)	6.75 [7] 67.7KM/H (8.6M)	9.30 [7] 70.6KM/H (8.6M)	11.86 [7] 70.3KM/H (8.9M)	14.48 [7] 68.6KM/H (7.6M)	17.16 [7] 40.9KM/H (6.6M)	10.41 59.3KM/H (7.9M)	17.16 [7]
7	French Fries	7	71.3KM/H	4.15 [8] 43.6KM/H (10.8M)	6.80 [8] 68.1KM/H (10.8M)	9.33 [8] 71.2KM/H (10.4M)	11.87 [8] 70.7KM/H (9.7M)	14.49 [8] 68.9KM/H (8.5M)	17.17 [8] 66.8KM/H (6.9M)	10.37 69.3KM/H (8.9M)	17.17 [8]

Information is produced by IsoLynx tracking system
 [] - Rank at each section
 () - Average meters to rail for section
 -- - No data available at section
 * - Estimated values

